# BAYES ESTIMATION OF LATENT CLASS MIXED MULTINOMIAL PROBIT MODELS

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## MOTIVATION

- Discrete choice models lie at the heart of many transportation models, e.g. the multinomial probit model.
- Modelling heterogeneity in preferences is indispensable in many applications and has been elaborated by imposing mixing distributions on the model coefficients.
- However, the literature does not provide much guidance for the specification of the mixing distribution apart from restrictive or computationally expensive strategies, e.g.
- model selection on standard parametric distributions,
- non-parametric approaches (cf. [1] and [2]).
- We present a new strategy, combining the ideas of
  - 1. a Bayesian framework (computational advantages),
  - 2. approximating mixing distributions by a mixture of normal distributions (high flexibility),
  - 3. weight-based updates on the number of latent classes (reduction of model assumptions).

## MODEL DEFINITION

Let person ns (n = 1, ..., N) utility of choice alternative j  $(j = 1, \ldots, J - 1)$  at choice occasion t  $(t = 1, \ldots, T)$  be

$$U_{ntj} = W'_{ntj}\alpha + X'_{ntj}\beta_n + \varepsilon_{ntj},$$

- where  $W_{ntj}$  ( $X_{ntj}$ ) is a vector of  $P_f$  ( $P_r$ ) differenced (wrt alternative J) characteristics of j as faced by n at tcorresponding to the fixed (random and decision makerspecific) coefficient vector  $\alpha \in \mathbb{R}^{P_f}$  ( $\beta_n \in \mathbb{R}^{P_r}$ ),
- $(\varepsilon_{nt1}, \ldots, \varepsilon_{nt(J-1)})' \sim \mathsf{MVN}_{J-1}(0, \tilde{\Sigma})$  with  $\tilde{\Sigma}_{11} = 1$ .

Let 
$$y_{nt}$$
 denote  $n$ s choice at  $t$ . Assuming rationality,  $y_{nt} = \sum_{j=1}^{J-1} j \cdot 1 \left( U_{ntj} = \max_{i} U_{nti} > 0 \right) + J \cdot 1 \left( U_{ntj} < 0 \text{ for all } j \right).$ 

We approximate the mixing distribution of  $(\beta_n)_n$  by a normal mixture, i.e.  $\beta_n \sim \sum s_c \cdot \text{MVN}_{P_r}(b_c, \Omega_c)$ . This is equivalent to introducing class allocation variables  $(z_n)_n$ with  $\operatorname{Prob}(z_n = c) = s_c$  and  $\beta_n \mid z, b, \Omega \sim \operatorname{MVN}_{P_r}(b_{z_n}, \Omega_{z_n})$ .

The proposed methodology to approximate underlying mixing distributions was tested in a series of simulations. Below, we exemplary present three of them, each having a data support of N = 3000 individuals being observed on making decisions at T = 30 choice occasions among J = 4 alternatives.



Simulation 2 is based on a stylized real world case: The population is separable into distinct groups which have different views on a certain choice attribute (e.g. out-of-vehicle travel time). This can be translated into a latent class setting. Here, we considered 3 latent classes (disaffirmation, indifference and affirmation). Our methodology performs well in approximating such a complex mixing distribution.



Another critical test of the approach constitutes its performance in applications with sign-restricted coefficients (e.g. for the alternative's price). In Simulation 3,  $P_r = 2$  random choice attributes were considered, the first of which was restricted to be non-positive. Visibly, a minor density mass (4.86%) is estimated also for positive values of the restricted coefficient. However, comparison tests indicate an acceptable approximation at a 5% significance level.

For more information, download the full paper here.

## SIMULATION RESULTS

Simulation 1 (left) and 2 (right)

In Simulation 1, the data originates from a latent class mixed multinomial probit model with C = 4 classes,  $P_f = 1$  fixed and  $P_r = 2$ random coefficients. The updating scheme was initialisied with 10 latent classes. Visibly, the true classes were reproduced.



Our Gibbs sampler builds upon the work of [3] and [4]. We apply conjugate and diffuse priors (their dependencies are abbreviated). Below, R denotes the number of iterations, B the number of discarded draws, and Q the thinning parameter. Within the second half of the burn-in period, the number of latent classes is updated.

#### Algorithm 1 GIBBS SAMPLER 1: for r = 1, ..., R do

۷.	$(s_1,\ldots,s_n)$
3:	draw $z$ from its
4:	for $c = 1,, C$
5:	draw $b_c \mid z, eta$
6:	draw $\Omega_c \mid z, eta$
7:	for $n = 1,, N$
8:	draw $\beta_n \mid \Omega, \delta$
9:	for $t = 1,,$
Ô٠	draw $U_{nt}$ ~
0.	100
1:	draw $\alpha \mid \beta, \Sigma, U$
0: 1: 2:	draw $\alpha \mid \beta, \Sigma, U$ draw $\Sigma \mid U, W$ ,
1: 2: 3:	draw $\alpha \mid \beta, \Sigma, U$ draw $\Sigma \mid U, W$ , if $B/2 < r \leq E$
1: 2: 3: 4:	draw $\alpha \mid \beta, \Sigma, U$ draw $\Sigma \mid U, W,$ if $B/2 < r \leq E$ call UPDATIN
<ol> <li>1:</li> <li>2:</li> <li>3:</li> <li>4:</li> <li>5:</li> </ol>	$\begin{array}{l} \operatorname{draw} \alpha \mid \beta, \Sigma, U \\ \operatorname{draw} \Sigma \mid U, W, \\ \operatorname{if} B/2 < r \leq E \\ \operatorname{call} UPDATIN \\ \operatorname{if} (B < r \leq R) \end{array}$
<ol> <li>1:</li> <li>2:</li> <li>3:</li> <li>4:</li> <li>5:</li> <li>6:</li> </ol>	draw $\alpha \mid \beta, \Sigma, U$ draw $\Sigma \mid U, W,$ if $B/2 < r \leq E$ call UPDATIN if $(B < r \leq R)$ save current

#### Algorithm 2 UPDATING SCHEME

1:	for $c = 1,, C$ do
2:	if $s_c < arepsilon_{\min}$ then
3:	remove class
4:	if $s_c > \varepsilon_{\max}$ the
5:	split class $c$
6:	$ \text{ if } \ b_c - b_{c^*}\  < \epsilon $
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## **BAYESIAN FRAMEWORK**

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 $(s_C) \mid z, \dots \sim D_C$ // C-dim. Dirichlet distribution conditional distribution do  $\beta, \Omega \cdots \sim \mathsf{MVN}_{P_n}$  $// P_r$ -dim. multivariate normal distribution  $eta, b, \dots \sim W_{P_{\pi}}^{-1}$ //  $P_r$ -dim. inverse Wishart distribution  $b, X, \Sigma, U, W, \alpha \sim \mathsf{MVN}_{P_r}$ T do  $\sim$  truncated MVN<sub>J-1</sub> via a sub-Gibbs sampler (cf. [5])  $U, X, \dots \sim \mathsf{MVN}_{P_f}$  $\alpha, X, \beta, \dots \sim W_{I-1}^{-1}$ 3 then IG SCHEME with current draws  $\wedge (r \mod Q = 0)$  then draws 17: normalize saved draws (cf. [6])

 $\varepsilon_{\text{distmin}}$  for any other class  $c^*$  then join classes c and  $c^*$  and average their parameters

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